Downlink Packet Scheduling for a Two-Layered Streaming Video Service in UMTS

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ABSTRACT

This paper presents a packet scheduling algorithm to manage the quality of service of a two layered video service in the downlink FDD mode of UMTS. The algorithm takes into account the expected interference and the OVSF code usage to schedule appropriately the different transmissions.

I. INTRODUCTION

W-CDMA access networks, such as the considered in UTRA-FDD proposal [1], provide an inherent flexibility to handle the provision of future 3G mobile multimedia services. In this scenario, Radio Resource Management (RRM) strategies will play a key role when optimizing air interface utilization. They are particularly relevant when dealing with packet multimedia flows that face different QoS requirements. Within this context, in this paper we focus in the QoS provision by means of UMTS of a downlink streaming video service that has two different quality layers, a basic flow that provides the minimum quality requirements and an enhancement layer that supplies additional information to improve reception depending on the available bandwidth [2]. Consequently, appropriate scheduling algorithms should be devised to manage the transmissions of the different flows while maximizing the use of the scarce downlink radio resources. It is worth noting that few studies aligned with 3GPP specifications are available in the open literature dealing with this problem. So the paper is organized as follows: in section II an overview of the downlink RRM is provided emphasizing how the power levels and codes are shared. In section III a description of the considered services and transport channels is given. In section IV the proposed packet scheduling algorithm is explained and performance results are presented in section V. Finally section VI summarizes the work done.

II. DOWNLINK RRM

Radio Resource Management strategies comprise of several algorithms responsible for the utilization of the air interface resources and, in general terms, they all have in common the monitoring of the cell load factor for adopting the algorithms decisions [3][4]. Efficient RRM algorithms are needed to guarantee QoS as well as to provide high capacity. In downlink direction the RRM functions include: admission control, congestion control, packet scheduling and code management, the later devoted to manage the OVSF code tree used to allocate physical channel orthogonality among different users. The centralized operation in the downlink direction gives room to radio resource allocation strategies operating at the short term and with the ability to consider many different aspects before allocation decisions are taken in order to meet some QoS constraints. Particularly, for services with tolerant delay requirements different users' flows can be scheduled to use shared channels. Decisions about who should transmit and its transmission parameters (i.e., transport format TF and power level) are the responsibility of the packet scheduler. Thus, any downlink RRM strategy should take into account the following two aspects to work properly:

II.A. Interference Management

Within a W-CDMA cell, all users share the common bandwidth and each new connection increases the interference level of other connections, affecting their quality expressed in terms of a certain (E_b/N_o) . For *n* users transmitting simultaneously at a given cell, the following inequality for the i-th user must be satisfied:

$$\frac{\frac{P_{Ti}}{L_p(d_i)} \times SF_i}{P_N + \chi_i + \rho \times \left[\frac{P_T - P_{Ti}}{L_p(d_i)}\right]} \ge \left(\frac{E_b}{N_o}\right)_i r$$
(1)
$$P_T = \sum_{i=1}^n P_{Ti}$$
(2)

 P_T being the base station transmitted power, P_{Ti} being the power devoted to the i-th user, χ_i representing the intercell interference observed by the i-th user, $L_p(d_i)$ being its path loss, *r* the channel coding rate and P_N the background noise. *SF* relates the bit duration to the chip period. ρ is the orthogonality factor due to the fact that orthogonal codes are used in the downlink direction. Differently from the uplink case, in downlink the intercell interference is user-specific since it depends on the user location, the base station transmitted power is shared by all users and the power allocations depend on the user location as well. Then, it is obtained that:

$$P_{T_{i}} \ge L_{p}(d_{i}) \frac{P_{N} + \chi_{i} + \rho \times \frac{P_{T}}{L_{p}(d_{i})}}{\frac{SF_{i}}{\left(\frac{E_{b}}{N_{o}}\right)_{i}}r} + \rho$$
(3)

Adding all n inequalities it holds that the total transmitted power to satisfy all the users demands should be:

$$P_{T,\max} \ge P_T = \frac{\sum_{i=1}^{n} \frac{\left(P_N + \chi_i\right)}{SF_i} L_p(d_i)}{\left(\frac{E_b}{N_o}\right)_i r} \qquad (4)$$

$$P_{T,\max} \ge P_T = \frac{\rho}{1 - \sum_{i=1}^{n} \frac{\rho}{SF_i} + \rho}$$

Claiming in (4) for the inherent positivity of P_N (i.e. P_N >0) leads to:

$$\eta_{DL} = \sum_{i=1}^{n} \frac{\left(\rho + \frac{\chi_{i} \times L_{p}(d_{i})}{P_{T}}\right)}{\frac{SF_{i}}{\left(\frac{E_{b}}{N_{o}}\right)_{i}} + \rho} < 1$$

$$(5)$$

The later expression is commonly known as the downlink load factor [4]. Additionally, physical limitations into the power levels are given by the maximum base station transmitted power, P_{Tmax} . The total transmitted power by the base station can be expressed in terms of the load factor as:

$$P_{T} = \frac{P_{N}}{(1 - \eta_{DL})} \sum_{i=1}^{n} \frac{L_{p}(d_{i})}{\frac{SF_{i}}{\left(\frac{E_{b}}{N_{o}}\right)_{i}}r} + \rho$$

$$(6)$$

where it can be observed that as the load factor increases the power demands also increase. Notice that, depending on how users are distributed in the cell, the downlink load factor is modified and also the required transmitted power varies.

II.B. Code Management

Apart from managing appropriately the power levels, another important scarce resource in the downlink are the OVSF codes. According to the properties of these codes, their availability is guaranteed whenever the Kraft's inequality is fulfilled, given by [5]:

$$\sum_{i=1}^{n} \frac{R_{b,i}}{R_b} \le SF_{\max} \tag{7}$$

where *n* is the number of users, $R_{b,i}$ their transmission bit rates and R_b the minimum bit rate (corresponding to spreading factor SF_{max} =512). In any case, the above inequality only guarantees the code availability, but in certain cases, depending on how codes are assigned some reallocations may be required.

III. SERVICES AND TRANSPORT CHANNELS

In UTRA FDD there are three types of channels to carry out downlink transmissions, namely [1]:

a) DCH (Dedicated CHannel): devoted to services with stringent transfer delay requirements, such as conversational services.

b) DSCH (Downlink Shared CHannel): devoted to services with tolerant transfer delay requirements, such as interactive services. It is associated to a DCH channel through which physical layer control information is transmitted. Transmission through these channels is subject to a packet scheduling policy.

c) FACH (Forward Access CHannel): devoted to services without QoS requirements.

Depending on the type of service to be provided, the previous channels should be managed and allocated appropriately. In this paper we are focusing on streaming video services, whose quality requirements deal with the achieved bit rate, the percentage of lost packets and the jitter of the delay rather than the endto-end delay. It is considered that streaming service allows an initial set-up delay that gives room to some packet transmissions before the video is reproduced. These packets can be stored in the mobile terminal buffer and the reproduction rate can be adjusted to the source rate. Then, the user can be unaware of the possible packet retransmissions because the stored buffer allows for a continuous packet flow. Of course, the retransmission capability would be limited by the initial buffering. Thus, this property gives some more room for scheduling the streaming service as packet retransmissions may play a role.

In order to differentiate quality levels, we assume for this service a two layered video application that is characterized by two different flows: a basic layer, with the minimum requirements for a proper visualization, and an enhancement layer, that contains additional information to improve the quality of the received images. We will assume that the basic layer will be transmitted through DCH channel while the enhancement layer will be transmitted only if there is capacity in the DSCH channels. For a certain user, the DSCH will be associated to the DCH channel carrying the basic layer. For this service a constant bit rate generation model is assumed. In order to save resources, the DCH channel operates at a fixed bit rate equal to the source bit rate, which means that a fixed number of transport blocks should be transmitted in each Transmission Time Interval (TTI). Consequently, there is no margin for carrying out retransmissions in the DCH channel. However, retransmissions may be useful to avoid having a very stringent BLER target that would limit the number of users in the system. Furthermore, the end-to-end delay of the service allows the use of retransmissions. As a result, it is assumed that the possible retransmissions of the basic layer can be carried out in the DSCH channel together with the enhancement layer, and having a higher precedence than the latter.

IV. PROPOSED PACKET SCHEDULING ALGORITHM

The proposed strategy allocates resources to the different flows that make use of the DSCH channel. It operates on a frame by frame basis (i.e., a frame is 10

ms) after the current transmissions for users in DCH channels are known. So the input parameters for this algorithm are:

- the number of users sharing the DSCH

- the number of transport blocks x waiting for transmission in the buffer of each user

- the required *Eb/No* target for each user, which depends on the BLER target to be achieved

- a measurement of each user's path loss $L_p(d_i)$

- a measurement of the other-to-own cell interference factor for each user:

$$f_{DL,i} = \frac{\chi_i L_p(d_i)}{P_T}$$
(8)

- the number of current transmissions in DCH channels, together with their corresponding transport format (TF) and *Eb/No* target

Taking into account all these parameters, and according to a generic scheduling behavior presented in [6] the algorithm performs the following steps in each frame:

IV.A. Prioritization

The first step consists in ordering the different users' requests in the DSCH depending on some priority criterion that takes into account the required QoS of each user. In particular, the priority table is derived from higher to lower priority according to:

- a. The higher the number of basic layer TBs to be retransmitted the higher the priority will be.
- b. For the same number of basic layer TBs, the priority is established according to the service credit concept, explained below. The higher the service credit of the enhancement layer the higher the priority

The service credit concept consists in monitoring the QoS that each flow has received in terms of bit rate and measuring the difference between the expected bit rate and the offered bit rate. The higher the difference, the higher the resources to be allocated (or equivalently the number of transport blocks that should be transmitted). So the "credit" that the system owes to the flow should be computed. This leads to the definition of the "service credit" (SCr) [7], that accounts for this difference and can be computed as follows in each TTI:

$$SCr(k) = SCr(k-1) + \frac{R_G}{TB} - NumTx(k-1)$$
(9)

where SCr(k) is the Service Credit for TTI=k, SCr(k-1) is the Service Credit in the previous TTI, R_G is the guaranteed bit rate measured in bits/TTI, TB is the number of bits of a Transport Block for the considered RAB and NumTx(k-1) is the number of successfully transmitted Transport Blocks in the previous TTI. It is worth noting that the quotient R_G/TB reflects the mean number of transport blocks that should be transmitted per TTI in order to keep the guaranteed mean bit rate. As a result, SCr(k) is a measure of the number of Transport Blocks that the connection should transmit in the current TTI to keep the guaranteed bit rate. For

example, if TB = 320 bits, $R_G = 32$ kb/s, and TTI=40 ms, 4 service credits are added in each TTI.

After computing the service credit, and assuming a total of x transport blocks in the buffer, the number of transport blocks to be transmitted in the current TTI would be:

$$numTB = \min(x, SCr(k), TB\max)$$
(10)

TBmax being the maximum number of Transport Blocks that can be transmitted per TTI depending on how the RAB is defined. Finally, the selected TF would be the one that allows to send *numTB* blocks.

The output of this phase is an ordered list of requests for the different users, each containing a *TF* value.

IV.B Resource allocation

Once requests are ordered, the next step consists in deciding whether or not they are accepted for transmission in the DSCH channel and which is the accepted TF. The limitations explained in section II dealing with interference and code availability are taken into account in this phase. To this end, it is required to estimate the expected load factor and transmitted power level once all the requests are accepted. Then, the expected load factor whenever there are n transmissions in the system in frame t (including both DCH and DSCH transmissions) is:

$$\eta(n,t) = \sum_{i=1}^{n} \frac{\left(\rho + f_{DL,i}(t-1)\right)}{\frac{SF_i}{\left(\frac{E_b}{N_o}\right)_i} r} + \rho$$
(10)

Similarly, the expected power is given by:

$$\widetilde{P}_{T}(n,t) = \frac{P_{N}}{(1-\widetilde{\eta}(n,t))} \sum_{i=1}^{n} \frac{L_{p}(d_{i})}{\frac{SF_{i}}{\left(\frac{E_{b}}{N_{o}}\right)_{i}}r}$$
(11)

It should be pointed out that the differences between the expected load factor and the real value can be due to the inaccuracies in the measurement of the other-toown-cell interference factor $f_{DL,i}$ and the path loss.

With this restrictions in mind, the algorithm executes for each request the rules in figure 1, assuming a total of *n* already granted transmissions. At the beginning, for the initially selected TF, the Kraft's inequality (7) is evaluated, afterwards, the expected load factor is compared with a threshold ϕ and finally the expected transmission power level should be below a fraction δ of the maximum transmitted power. If all three conditions hold, transmission is granted for this request during one TTI, otherwise, the transport format is reduced by one, or equivalently, the transmission bit rate is reduced. If this is not possible, the request should wait for the next frame. It should be mentioned that control parameters ϕ and δ (both <1) should be appropriately set in order to take into account the possible fluctuations between the expected values and the real measurements.



Fig. 1 Resource allocation process

V. RESULTS AND DISCUSSION

In order to evaluate the performance of the proposed strategy, a system level simulator platform has been developed by means of the OPNET simulation tool. The system model considers a multicellular layout with 7 omnidirectional base stations. The distance between base stations is 1 km. Mobiles are uniformly distributed in the scenario. The mobility and propagation models are defined in [8] with a mobile speed of 50 km/h and a shadowing fading with 10 dB deviation. Maximum transmitted power by the base station is 43 dBm. The traffic generation model assumes a CBR model with 32 kb/s for the basic layer and 32 kb/s for the enhancement layer, so each 40 ms a packet with 1280 bits is generated for each flow. Only traffic in the downlink direction is considered. For the uplink direction only an ideal return channel to transmit control messages (i.e., acknowledgements and measurements) is assumed. For each packet a maximum transfer delay of 1s is considered, if the maximum delay is overcome, the packet is discarded.

The radio access bearer considered for the basic layer has a Transmission Time Interval (TTI) of 40 ms, the transport block size is 320 bits (without including RLC/MAC headers) and it has two possible transport formats: TF0 (no transmission) or TF1 (allowing the transmission of 4 transport blocks). For the enhancement layer the radio access bearer contains 6 transport formats, defined in Table I, that are selected depending on how the scheduling algorithm behaves. The physical control channel information for DSCH is transmitted through the DCH of the basic layer.

Table I. TFs for the streaming enhancement RAB.

8		
TrCH type		DSCH
TB sizes, bit		320 bits (payload) + 16 bits
		(MAC/RLC header)
TFS	TF0, bits	0×320
	TF1, bits	1×320 (8 Kb/s)
	TF2, bits	2×320 (16 Kb/s)
	TF3, bits	4×320 (32 Kb/s)
	TF4, bits	8×320 (64 Kb/s)
	TF5, bits	16×320 (128 Kb/s)
TTI, ms		40

The characterization of the physical layer, including the rate 1/3 turbo code effect is taken from [9]. The BLER target is set to 1%. The total number of users in the scenario has been varied between 100 and 160 (for less than 100 users both the streaming and enhancement layers can be provided at their expected rate of 32 kb/s, so the interest in the analysis arises when the system has more than 100 users).

One of the most relevant parameters in the design of the packet scheduling algorithm relays on the threshold ϕ of the estimated load factor $\eta(n+1,t)$ when deciding the granted transmissions. Particularly, if ϕ is too high, the difference between the estimated and the real values can lead the system to a situation where no available power exists that satisfies at the same time all the users requirements, thus obtaining BLER values higher than the target one for both basic and enhancement layers. On the other hand, if ϕ is too low less problems will exist for basic transmissions at the expense that a lot of enhancement requests will be postponed. This trade-off can be observed in Figs. 2 and 3. The first one presents the average bit rate obtained during a streaming session for the enhancement layer depending on threshold ϕ . $\delta=1$ has been assumed. The basic layer is not presented since its achieved bit rate is always 32 kb/s, with a slight reduction for the case 160 users and $\phi=1$. This reduction can be observed in Fig. 3 where the percentage of lost packets (due to expiring the maximum delay) is presented for both basic and enhancement layers as a function of the number of users. The reason for this degradation is the increase in the BLER due to errors in the estimation of the offered load. Something similar occurs for the enhancement layer, where most of the packets are lost. From both figures it can be concluded that the selection ϕ =0.95 provides the best behavior since it achieves the maximum bit rate for the enhancement without degrading the quality of the basic layer. Notice also that thanks to the retransmissions, the packet loss ratio is zero for the basic flow whenever $\phi <=0.95$ even for high loads.





Fig. 3.- Percentage of lost packets

Furthermore, Fig. 4 shows the jitter of the packet delay, that is one of the main QoS requirements for a streaming service. For the basic flow, it can be observed that, a part from the case ϕ =1, the jitter is below 1 TTI (40 ms). For the enhancement case, the jitter is somewhat higher than the basic due to the packet scheduling operation. The value of the jitter impacts the buffer dimensioning at the receiver side to guarantee that each flow is delivered to the user in a continuous way. Consequently, the maximum allowable jitter will depend on the specific buffer capabilities.

VI. CONCLUSIONS

This paper has presented a packet scheduling strategy that deals with the provision of QoS to a two layered video streaming application by jointly considering the use of DCH and DSCH channels. It has been shown that managing retransmissions appropriately can be suitable to reduce packet losses for both layers. In order to decide the granted transmissions, the algorithm takes into account an estimation of the expected load factor, that must be below a threshold. The influence of this threshold has been analyzed to maximize the rate of the enhancement flow while at the same time meeting the requirements of the basic layer.



Fig. 4.- Jitter of the packet delay

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